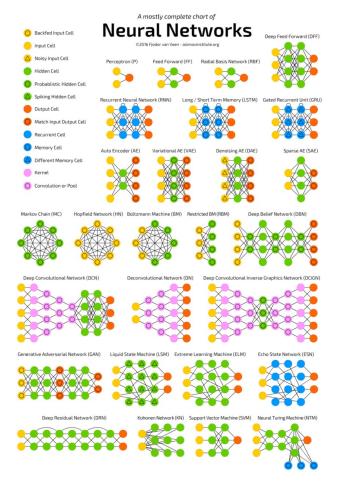
# Transformers

CSCI 4360/6360 Data Science II

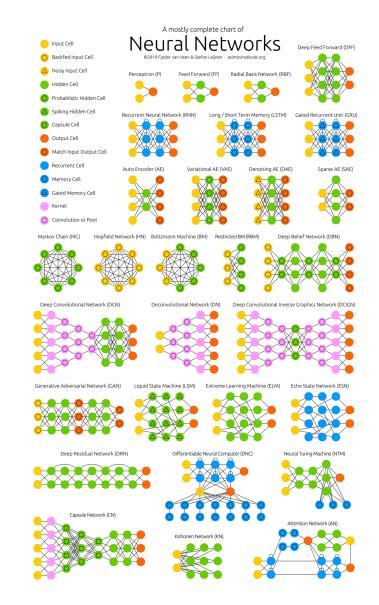
#### The Neural Network Zoo

 <u>http://www.asimovinstitute.org</u> /neural-network-zoo/



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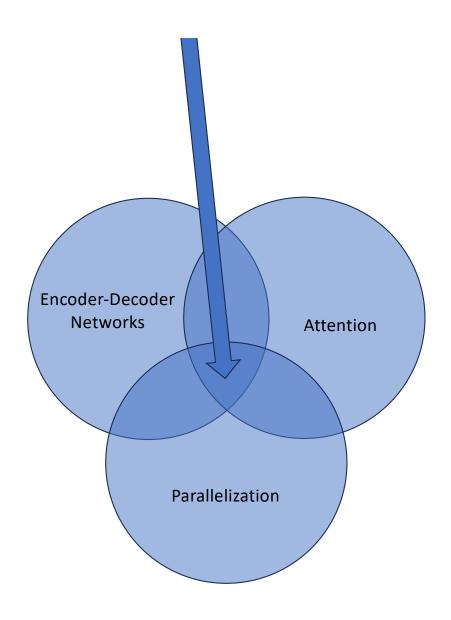


#### Neural Networks 😑 Input Cell Deep Feed Forward (DFF) O Backfed Input Cell 🛆 Noisy Input Cell Perceptron (P) Feed Forward (FF) Radial Basis Network (RBF) 🛑 Hidden Cell The Neural Network Zoo O Probablistic Hidden Cell Spiking Hidden Cell 1emory (LSTM Capsule Cell Output Cell O Match Input Output Cel Recurrent Cell enoising AE (DAE O Memory Cell • <u>http://www.asimovinstitute.org</u> Gated Memory Cell Kernel /neural-network-zoo/ Convolution or Pool Markov Chain (MC) Hopfield Net versarial Network (GAN) Liquid State Machine (LSM) Extreme Learning Machine (ELM) Echo State I Today Deep Residual Network (DRN)

A mostly complete chart of

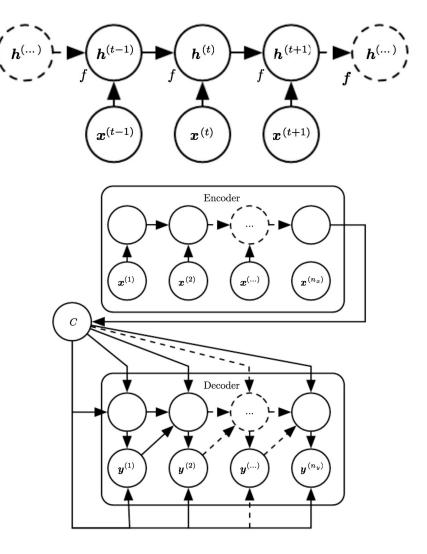
### Transformers

• A confluence of multiple technologies and theories



#### **RNNs** revisited

- Recurrences
  - Input + hidden state
  - LSTM "forget" gate
  - Encoder-decoder
- Sequential architecture precludes parallelization
- Lot of information crammed into  $h_t$
- "Catastrophic forgetting"



## Transformers

- Transductive model
- Relies entirely on selfattention mechanisms
- No sequence-aligned RNNs or convolutions



## Transformer architecture

- Encoder
  - Maps input sequence (x<sub>1</sub>,...,x<sub>n</sub>) to a representation sequence (z<sub>1</sub>,...,z<sub>n</sub>)
- Decoder
  - From sequence z, generates output sequence (y<sub>1</sub>,...,y<sub>m</sub>)
  - Model is autoregressive
- Stacked self-attention and point-wise fully connected layers
- Positional encodings allow for fully parallelized encodings

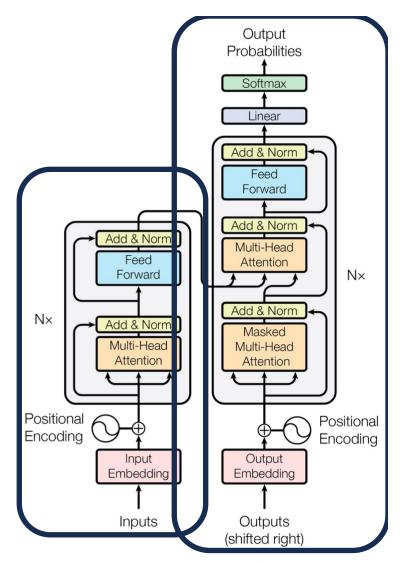


Figure 1: The Transformer - model architecture.

#### Attention

- Maps:
  - A query
  - A set of key-value pairs

• Query, Key, Value

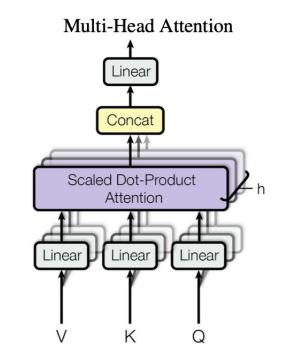
• An output

- Weighted sum of values
- Weight assigned to each value is output of a "compatibility function" of query with corresponding key
- Vectors (in theory)
  - Matrices in practice (i.e., many queries/keys/values in parallel)

Attention
$$(Q, K, V) = \operatorname{softmax}(\frac{QK^T}{\sqrt{d_k}})V$$

#### Attention

- In 2017 paper, Attention = "Scaled Dot-Product Attention"
- Multi-head attention
  - Linearly project Q, K, and V h times with different learned projections
  - Attention performed in parallel on each projection
  - Concatenated to compute final attention values



 $\begin{aligned} \text{MultiHead}(Q, K, V) &= \text{Concat}(\text{head}_1, ..., \text{head}_h)W^O \\ \text{where head}_i &= \text{Attention}(QW_i^Q, KW_i^K, VW_i^V) \end{aligned}$ 

#### Attention and Self-Attention

- Encoder-decoder attention layers
  - Q from previous decoder layer
  - K, V from output of encoder
  - Every position in the decoder can attend to all input positions
- Encoder contains self-attention layers
  - Q, K, V all come from the same place (output of previous encoder layer)
  - Each position in encoder can attend to all positions in previous encoder layer
- Decoder contains self-attention layers
  - Each position in decoder can attend to all positions in previous decoder layer **up to and including the current position** (but not past it!)

#### Connections to Support Vector Machines

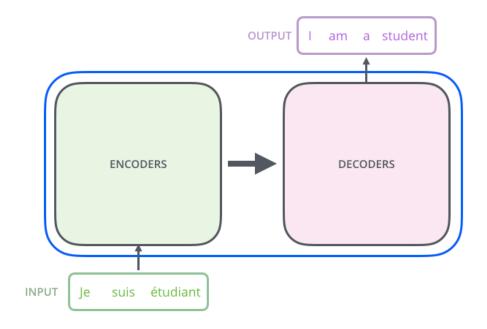
- SVMs were all the rage in the late 90s and early 2000s
  - Neural networks had been a "dead end" since early 90s
- 1-layer self-attention Transformers = hard-margin SVM
- Multilayer transformers = hierarchy of SVMs

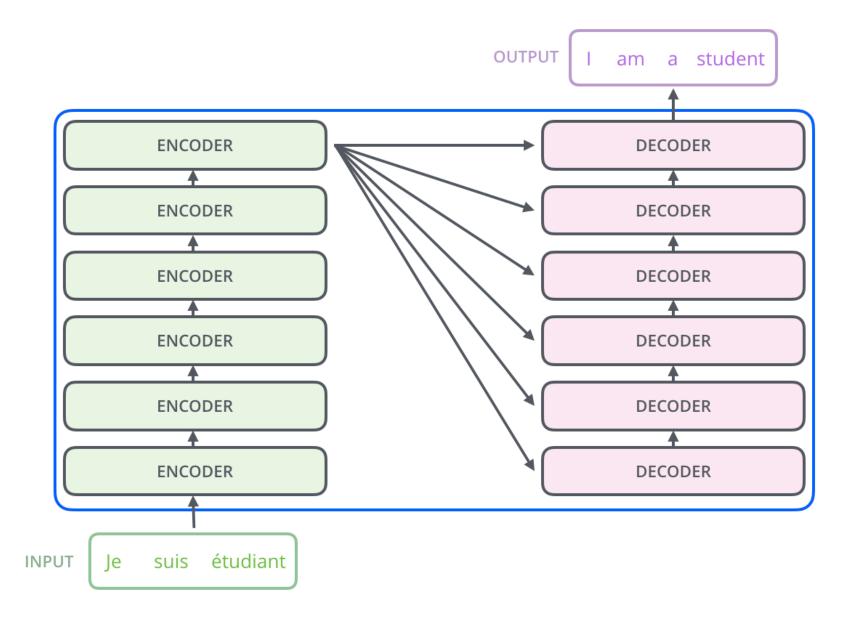
Transformers as Support Vector Machines

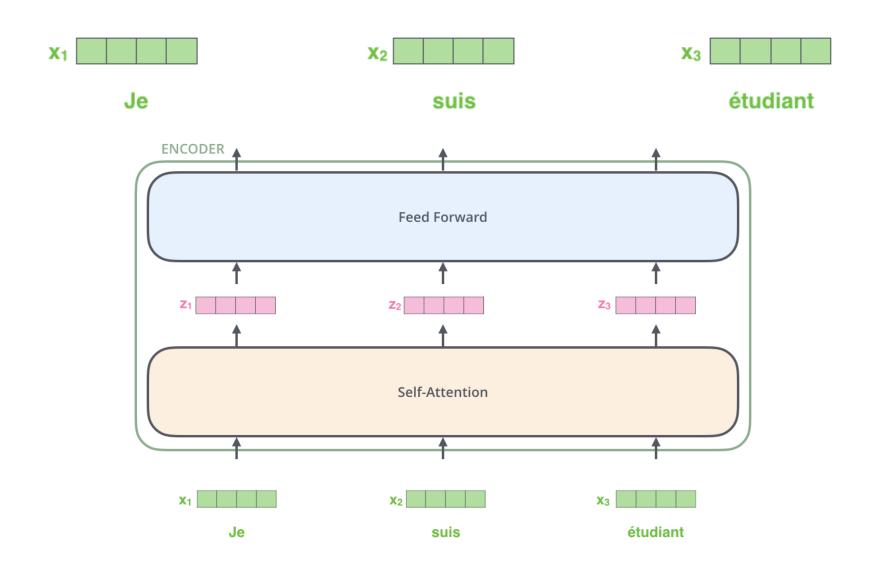
Davoud Ataee Tarzanagh<sup>1\*</sup> Yingcong Li<sup>2\*</sup> Christos Thrampoulidis<sup>3</sup> Samet Oymak<sup>4†</sup>

#### Let's add some pictures

• Courtesy of The Illustrated Transformer







#### Input

#### Thinking

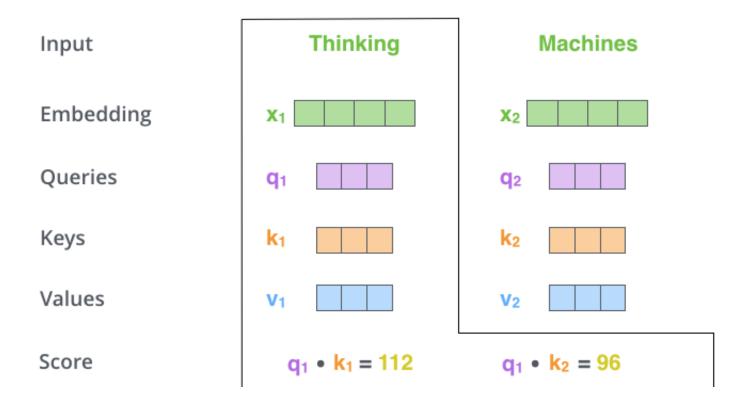
Machines

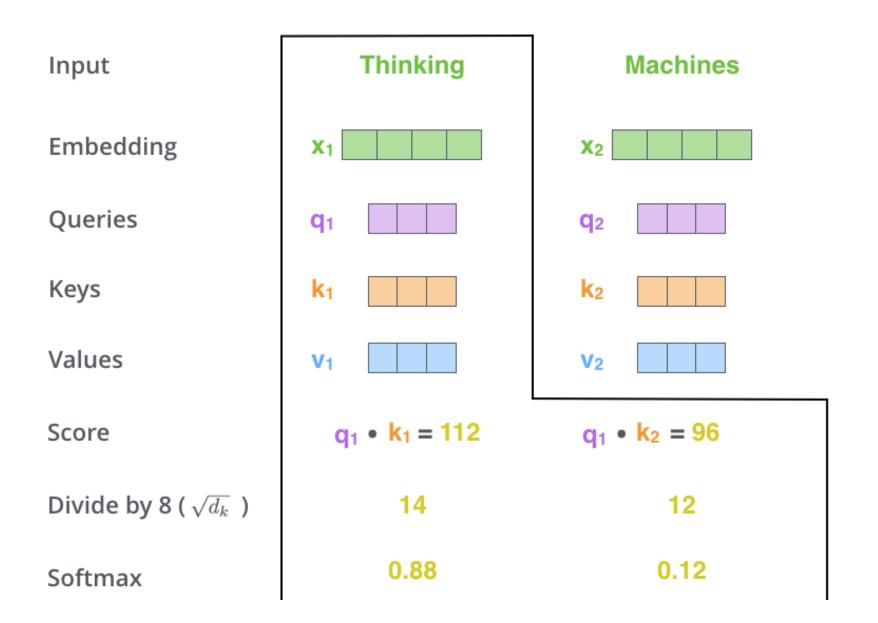
Embedding				blue			the	verdant	forest	
Queries		$ \stackrel{\bullet}{\to} \bullet$	$ \stackrel{\bullet}{\stackrel{\bullet}{=}} \stackrel{\bullet}{\stackrel{\bullet}{=} \stackrel{\bullet}{\stackrel{\bullet}{=}} \stackrel{\bullet}{\stackrel{\bullet}{=} \stackrel{\bullet}{=} \stackrel{\bullet}{\stackrel{\bullet}{=} \stackrel{\bullet}{\to} \stackrel{\bullet}{=} \stackrel{\bullet}{\stackrel{\bullet}{=} \stackrel{\bullet}{\to} \stackrel{\bullet}{=} \stackrel{\bullet}{\to} \stackrel{\bullet}{=} \stackrel{\bullet}{\to} \stackrel{\bullet}{=} \stackrel{\bullet}{\to} \stackrel{\bullet}{\bullet} \stackrel{\bullet}{\to} \stackrel{\bullet}{\to} \stackrel{\bullet}{\to} \stackrel{\bullet}{\to} \stackrel{\bullet}{\to} \stackrel{\bullet}{\bullet} \stackrel{\bullet}{\to} \stackrel{\bullet}{\bullet} \stackrel{\bullet}{\to} \stackrel{\bullet}{\to} \stackrel{\bullet}{\bullet} \stackrel{\bullet}{\bullet} \stackrel{\bullet}{\to} \stackrel{\bullet}{\bullet} \stackrel{\bullet}{\bullet} \stackrel{\bullet}{\bullet} \stackrel{\bullet}{\to} \stackrel{\bullet}{\bullet} \bullet$	Ĕ <sub>3</sub> ₩ <sub>Q</sub> Q <sub>3</sub>	$\vec{E}_4$ $\vec{Q}_4$	$\overrightarrow{\mathbf{E}}_{5}^{5}$	$\mathbf{E}_{6}^{W_Q}$	$\vec{E}_7 \rightarrow \vec{Q}_7$	$\begin{array}{c} \bullet \\ \vec{\mathbf{E}}_8 \\ \bullet \\ \vec{\mathbf{Q}}_8 \end{array}$	
	$\mathbf{a} \! \rightarrow \! \vec{\mathbf{E}}_1 \stackrel{W_k}{\longrightarrow} \vec{\mathbf{K}}_1$	<b>KQ</b> <sub>1</sub>	$\vec{\mathbf{K}}_1 \cdot \vec{\mathbf{Q}}_2$	$\vec{\mathbf{K}}_1 \cdot \vec{\mathbf{Q}}_3$	$\vec{\mathbf{K}}_1 \cdot \vec{\mathbf{Q}}_4$	$\vec{\mathbf{K}}_1 \cdot \vec{\mathbf{Q}}_5$	$ec{\mathbf{K}}_1 ullet ec{\mathbf{Q}}_6$	KQ7	$ec{\mathbf{K}}_1\!\cdot\!ec{\mathbf{Q}}_{\mathbf{k}}$	
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	$\boxed{\text{blue}} \rightarrow \vec{\mathbf{E}}_3 \xrightarrow{W_k} \vec{\mathbf{K}}_3$	$\vec{\mathbf{K}}_{3} \cdot \vec{\mathbf{Q}}_{1}$	$\vec{\mathbf{K}}$	$\vec{\mathbf{K}}_3 \cdot \vec{\mathbf{Q}}_3$	$\vec{\mathbf{K}}_3 oldsymbol{Q}_4$	$ec{\mathbf{K}}_3 \boldsymbol{\cdot} ec{\mathbf{Q}}_5$	$\vec{\mathbf{K}}_3 \cdot \vec{\mathbf{Q}}_6$	$ec{\mathbf{K}}_3 ullet ec{\mathbf{Q}}_7$	$\vec{\mathbf{K}}_3 \cdot \vec{\mathbf{Q}}_8$	
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	$\boxed{\text{roamed}} \rightarrow \vec{\mathbf{E}}_5 \xrightarrow{W_k} \vec{\mathbf{K}}_5$	$\vec{\mathbf{K}}_5 \cdot \vec{\mathbf{Q}}_1$	$\vec{\mathbf{K}}_5 \cdot \vec{\mathbf{Q}}_2$	ĸ <b>o</b>	$\vec{\mathbf{K}}_5\cdot\vec{\mathbf{Q}}_d$	$\vec{\mathbf{K}}_5 \cdot \vec{\mathbf{Q}}_5$	$ec{\mathbf{K}}_5\!\cdot\!ec{\mathbf{Q}}_6$	ĸ <b>O</b> 7	$ec{\mathbf{K}}_5\!\cdot\!ec{\mathbf{Q}}_8$	
	$\boxed{\text{the}} \rightarrow \vec{\mathbf{E}}_6 \xrightarrow{W_k} \vec{\mathbf{K}}_6$	$\vec{\mathbf{K}}_6\cdot\vec{\mathbf{Q}}$	K <sub>O</sub> 2	$\vec{\mathbf{K}}_{6} \cdot \vec{\mathbf{Q}}_{3}$	$\vec{\mathbf{K}}_6 \mathbf{O} \vec{\mathbf{Q}}_4$	$\vec{\mathbf{K}}_6 \bullet \vec{\mathbf{Q}}_5$	$\vec{\mathbf{K}}_6\cdot\vec{\mathbf{Q}}_6$	$ec{\mathbf{K}}_6\!\cdot\!ec{\mathbf{Q}}_7$	$\mathbf{\vec{k}}_{6}\cdot\mathbf{\vec{Q}}_{8}$	
	$\overrightarrow{\text{verdant}} \rightarrow \vec{\mathbf{E}}_7 \xrightarrow{W_k} \vec{\mathbf{K}}_7$	$\vec{\mathbf{K}}_{7} \mathbf{\Theta} \vec{\mathbf{Q}}_{1}$	$\vec{\mathbf{K}}_7 \cdot \vec{\mathbf{Q}}_2$	$\vec{\mathbf{K}}_7 \bullet \vec{\mathbf{Q}}_3$	$\vec{\mathbf{K}}_7 \cdot \vec{\mathbf{Q}}_1$	$\vec{\mathbf{K}}_7 ullet \vec{\mathbf{Q}}_5$	$\vec{\mathbf{K}}_{f}$		$\vec{\mathbf{K}}_7\cdot\vec{\mathbf{Q}}_8$	
Values	<b>V</b> 1				<b>V</b> 2					

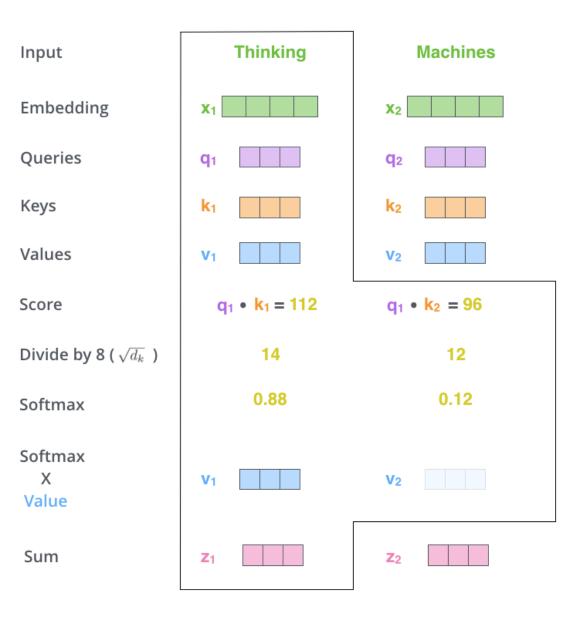
WQ

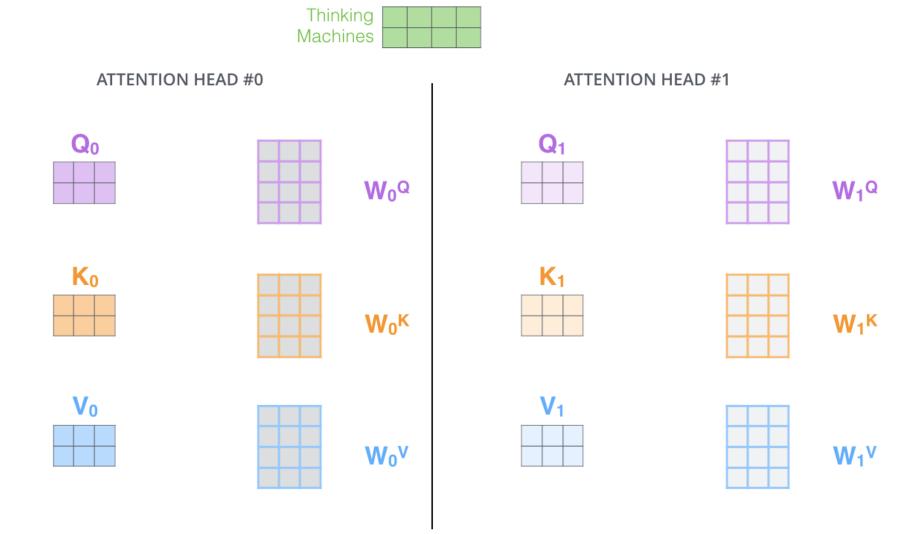
Wκ

WV





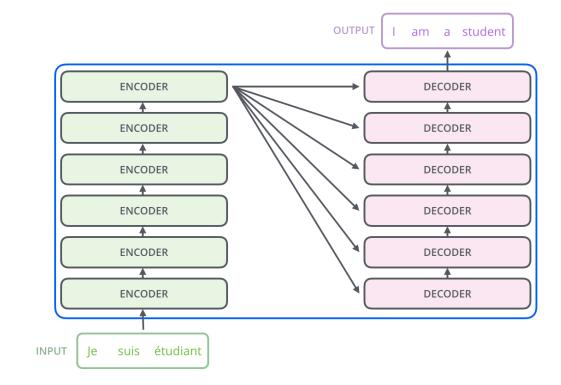




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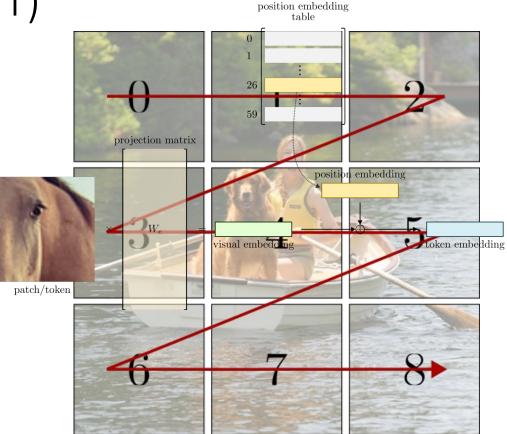
#### What about the decoder?

- Final K, V from encoder sent to each decoder
- Each decoder focuses its attention on "correct" positions of encoder



### Vision Transformers (ViT)

- Built on the same principles
- Patches = tokens
  - Still have positional encodings
  - Are still embedded in the first encoder step
- Attention = dictionary lookup
  - dictionary[query] = value
  - If key==query, return value
  - "Soft" selection
- Everything else is the same!

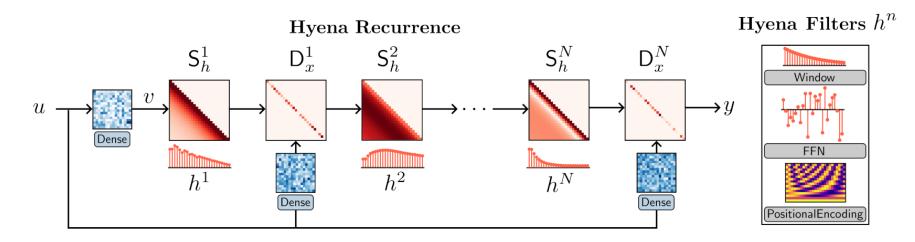


#### Transformer limitation

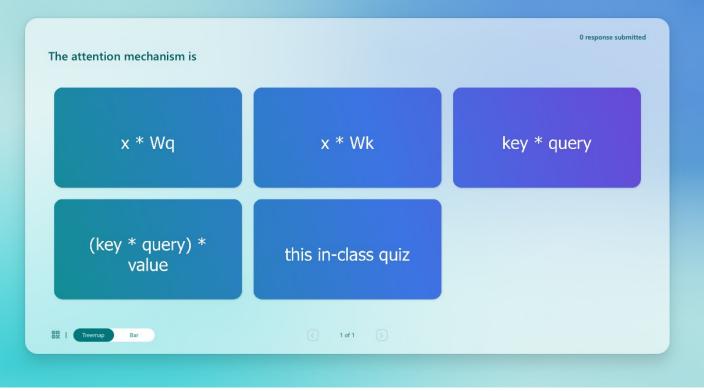
- Attention mechanism is still  $O(n^2)$ 
  - Each token compared to each other token
  - Subquadratic methods exist but rely on low-rank / sparse approximations, and require dense Attention layers
  - Ultimately limits the possible sequence length *n* (context window)

#### Hyena

- Subquadratic drop-in Attention replacement
  - Hyena operator
- Long convolutions
  - filter sizes as long as the input
- Data-controlled gating (element-wise multiplication)
  - Convolutions in FFT (i.e., frequency) space are element-wise multiplications!







#### Conclusions

- Transformer architecture for modeling sequences (of text or images)
  - Throws out recurrences of RNNs for more parallel training
  - Ditching recurrences also allows for arbitrary context windows
- Still use the encoder-decoder architecture
  - Input embeddings are critical to the overall performance
- Attention
  - Transformer allows for all tokens to "attend" to all other tokens
  - Can model extremely long-distance dependencies (spatially or sequentially)
  - Only drawback is quadratic computation time
- Hyena operator
  - Clever use of FFT-based convolutions and Toeplitz matrices to accelerate standard computations and produce subquadratic performance

#### References

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- The Illustrated Transformer <a href="https://jalammar.github.io/illustrated-transformer/">https://jalammar.github.io/illustrated-transformer/</a>
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  <a href="https://arxiv.org/abs/2302.10866">https://arxiv.org/abs/2302.10866</a>
- 3Blue1Brown: Transformers: How LLMs work, explained visually <u>https://www.youtube.com/watch?v=wjZofJX0v4M</u>

• 3Blue1Brown: Attention in Transformers, step-by-step https://www.youtube.com/watch?v=eMlx5fFNoYc

#### Up next

- Final Project Update #2 is due TONIGHT!
- Homework 5 is due next Tuesday! (April 15)
- Next Tuesday & Thursday (April 15 & 17): last lectures of the class
- April 22, 23, and 24: Final Project Presentations
  - If you have given me a preference for presentation day, yay!
  - If you have not, your time will be **randomized & determined each day!**
  - Presentations are 20 minutes, with 2-3 minutes for questions
  - Please come support your classmates even after you have presented