CSCI 4360/6360 Data Science II

Embeddings

- Principal Components Analysis (PCA)
 - Sparse & Kernel PCA (*last* Thursday!)
- Independent Components Analysis (ICA)
- Non-negative Matrix Factorization (NMF)
- Locally-linear Embeddings (LLE)
- Dictionary Learning (today!)

Linear

Sparse &

Jon-Gaussian

Von-negative

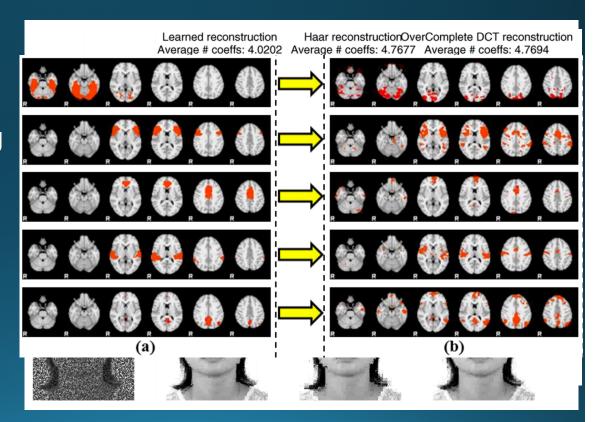
Nonlinear

Sparse &

Nonlinear

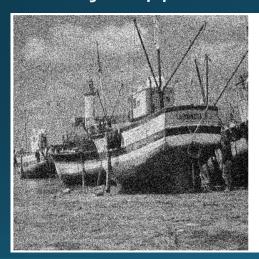
- "Given a set of signals belonging to a certain class, one wishes to extract the relevant information by identifying the generating causes; that is, recovering the elementary signals (atoms) that efficiently represent the data."
 - Regularization, Optimization, Kernels, and Support Vector Machines, Ch. 2
- Every embedding strategy ever?

- Sparse coding
- *l*^p sparsity
- Hierarchical sparse coding
- K-SVD
- Elastic net



Motivations

 Dictionary learning is ideally formulated for image denoising (and is indeed a major application of dictionary learning)





Measurements (image)

$$y = x_{orig} + w$$
Original image

Noise

Motivations

$$y = x_{orig} + w$$

• Easily converted to an energy minimization problem

$$E(\vec{x}) = ||\vec{y} - \vec{x}||_2^2 + Pr(\vec{x})$$

Some classical priors

- Smoothness
- Total variation
- Wavelet sparsity
- Lasso
- ...

$$\begin{array}{c|c} \lambda ||\mathcal{L}\vec{x}||_2^2 \\ \lambda ||\nabla \vec{x}||_1^2 \\ \lambda ||W\vec{x}||_1 \\ \lambda ||\vec{x}||_1 \end{array}$$

Energy minimization becomes a MAP estimation!

- We have our data X
- and wish to represent it using some small number k atoms (k <<< n)
- When combined with coefficients, the linear combinations with the atoms should yield a nearly complete representation of X

$$X = [\vec{x}_1, \vec{x}_2, ..., \vec{x}_n]^T \in \mathbb{R}^{n \times m}$$

$$\vec{x}_i \cong \sum_{j=1}^k \theta_{ji} \vec{b}_j, \forall i = 1, ..., n$$

$$B = \begin{bmatrix} \vec{b}_1, \vec{b}_2, ..., \vec{b}_k \end{bmatrix}^T \in \mathbb{R}^{k \times m}$$

$$\Theta = \begin{bmatrix} \vec{\theta}_1, \vec{\theta}_2, ..., \vec{\theta}_n \end{bmatrix}^T \in \mathbb{R}^{n \times k}$$

This gives the minimization

$$\min_{B,\Theta} \sum_{i=1}^{n} \left(||\vec{x}_i - B\vec{\theta}_i||_q^q + h(\vec{\theta}_i) \right)$$

where *h* promotes sparsity in the coefficients, and *B* is chosen from a constraint set

The general dictionary learning problem then follows

$$\phi(\Theta, B) = \frac{1}{2}||X - B\Theta||_F^2 + h(\Theta) + g(B)$$

where specific choices of h and g are what differentiate the different kinds of dictionary learning (e.g. hierarchical, K-SVD, etc)

Dictionary Learning vs PCA

- Remember the operational definition of PCA?
- 1. Orthogonal projection of data
- Lower-dimensional linear space known as the principal subspace
- Variance of the projected data is maximized

- Dictionary Learning (sparse coding)
 - 1. Minimize reconstruction error
 - 2. Linear combination of *αtoms*
 - 3. Sparse, overcomplete basis

Two definitions of PCA

Objectives are reconstruction, sparsity, and redundancy

Maximizing Variance

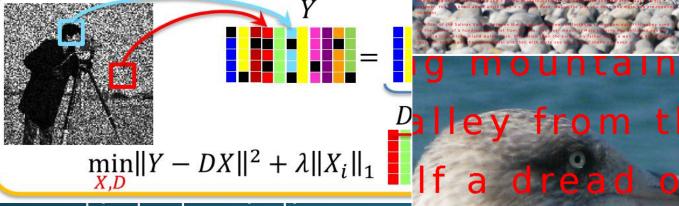
Minimizing Roonstruction Error

$$Pr(\mathbf{x}) = \lambda ||\alpha||_0 ext{ for } \mathbf{x} pprox \mathbf{D} lpha$$

$$\underbrace{\left(\mathbf{x}\right)}_{\mathbf{x} \in \mathbb{R}^m} = \underbrace{\left(\begin{array}{c|c} \mathbf{d}_1 & \mathbf{d}_2 & \cdots & \mathbf{d}_p \end{array}\right)}_{\mathbf{D} \in \mathbb{R}^{m \times p}} \underbrace{\left(\begin{array}{c} \alpha[1] \\ \alpha[2] & \vdots \\ \alpha[p] \end{array}\right)}_{\alpha \in \mathbb{R}^p, \mathsf{sparse}}$$

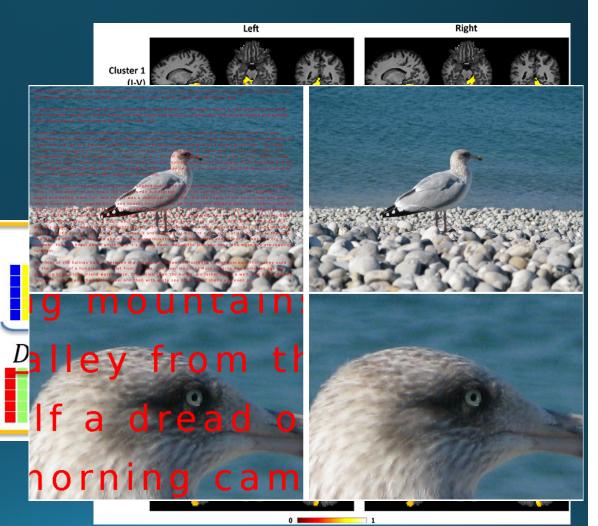


- Image denoising
 - Sparse basis forces out noise



object categorization

 Image restoration & inpainting



B is typically implicitly constrained to fall within a convex set C of the kx m reals, to make optimization tractable

General formulation

$$\phi(\Theta, B) = \frac{1}{2}||X - B\Theta||^2 + h(\Theta) + g(B)$$

More common: set g to identity*, and h to L₁ norm

$$\phi(\Theta, B) = \min_{B \in \mathcal{C}} \frac{1}{2} \sum_{i=1}^{n} ||\vec{x}_i - B\vec{\theta}_i||_2^2 + \lambda ||\vec{\theta}_i||_1$$

Optimization

Problems with the objective function?

$$\phi(\Theta, B) = \min_{B \in \mathcal{C}} \frac{1}{2} \sum_{i=1}^{n} ||\vec{x}_i - B\vec{\theta}_i||_2^2 + \lambda ||\vec{\theta}_i||_1$$

- Squared loss is convex
- Regularization is convex
- Squared loss + regularization is not convex
- Even worse, often non-smooth

Optimization

- Alternating minimization algorithm
 - Two-block Gauss-Seidel

 $A\vec{x} = \vec{b}$ $A = L_* + U$ $L_*\vec{x}^{(k+1)} = \vec{b} - U\vec{x}^{(k)}$

- Streaming online learning
 - At iteration (or minibatch) t, signal x_t and sparse code θ_t are computing using the current dictionary

$$\vec{\theta}_t = \arg\min_{\vec{\theta}} \frac{1}{2} ||\vec{x}_t - B_{t-1}\vec{\theta}||_2^2 + \lambda ||\vec{\theta}||_1$$

• Which can then be used to update the dictionary

$$g_t(B) = \frac{1}{t} \sum_{i=1}^{t} \frac{1}{2} ||\vec{x}_i - B\vec{\theta}_i||_2^2 + \lambda ||\vec{\theta}_i||_1$$

g can be efficiently solved using block coordinate descent on columns of B

Rank-1 Dictionary Learning (R1DL)

• KDD 2016

Scalable Fast Rank-1 Dictionary Learning for fMRI Big Data Analysis

"Scalable fast"

R₁DL

- Reformulates dictionary learning as an alternating least-squares problem
 - (embraces the optimization procedure)
- Uses o-"norm" instead of L₁
 - Given rank-1 formulation, this is an inexpensive way of guaranteeing sparsity
- Iteratively learns rank-1 dictionary atoms until k have been found
 - "Deflates" data matrix on each iteration

R₁DL

Energy function L

$$L(\vec{u}, \vec{v}) = ||S - \vec{u}\vec{v}^T||_F$$

- Data matrix S, vectors u and v
 - || *U* || = 1
 - $||v||_0 \le r$, where r is the sparsity constraint (literally, # of nonzero elements in v)
- Iterate until convergence of υ (atoms) and υ (sparse codes)

$$\vec{v} = \arg\min_{\vec{v}} ||S - \vec{u}\vec{v}^T||_F \quad \vec{u} = \arg\min_{\vec{u}} ||S - \vec{u}\vec{v}^T||_F = \frac{Sv}{||S\vec{v}||}$$
$$||\vec{u}^{(j+1)} - \vec{u}^{(j)}|| < \epsilon$$

- ullet "Deflate" data matrix $S^{(t+1)} = S^{(t)} ec{u} ec{v}^T$
- Repeat until k atoms & sparse codes are learned

Summary

- Dictionary learning is focused on developing a basis of *αtoms* and *coefficients*
 - Coefficients are sparse
 - Atoms form an overcomplete representation of the data
 - Chosen to minimize reconstruction error
- Explicitly factorizes out noise
 - Can be customized in the form of a prior
- Optimization is often non-convex and non-smooth, requiring alternating minimization strategies or online learning
- R1DL focuses on leveraging optimization strategies to iteratively learn the basis, one atom at a time
- Other variants include K-SVD, Hierarchical DL, and Elastic Net

Questions?

Course Details

- Assignment 5 is out!
 - The final assignment!
 - Due Tuesday, November 5
- Students in the other class have entered Slack!
 - Start chatting with them ©
 - ...technically required for Assignment 5
- Next week:
 - Conclude dimensionality reduction on Tuesday
 - Begin neural networks on Thursday
 - November is all NNs, all the time

References

- "Sparse coding with an overcomplete basis set: A strategy employed by V1?", http://www.sciencedirect.com/science/article/pii/Soo42698997001697
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- "K-SVD: An Algorithm for Designing Overcomplete Dictionaries for Sparse Representation", http://www.cs.technion.ac.il/~freddy/papers/120.pdf
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- "Dictionary learning for sparse coding: Algorithms and convergence analysis", https://pdfs.semanticscholar.org/284d/9c37o2b882oe2bd89b1c96532f12b3afb 336.pdf
- "Sparse Coding and Dictionary Learning for Image Analysis", https://lear.inrialpes.fr/people/mairal/tutorial_iccvog/tuto_part2.pdf